

# Chapter 6

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## Event Control Blocks

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# Outline

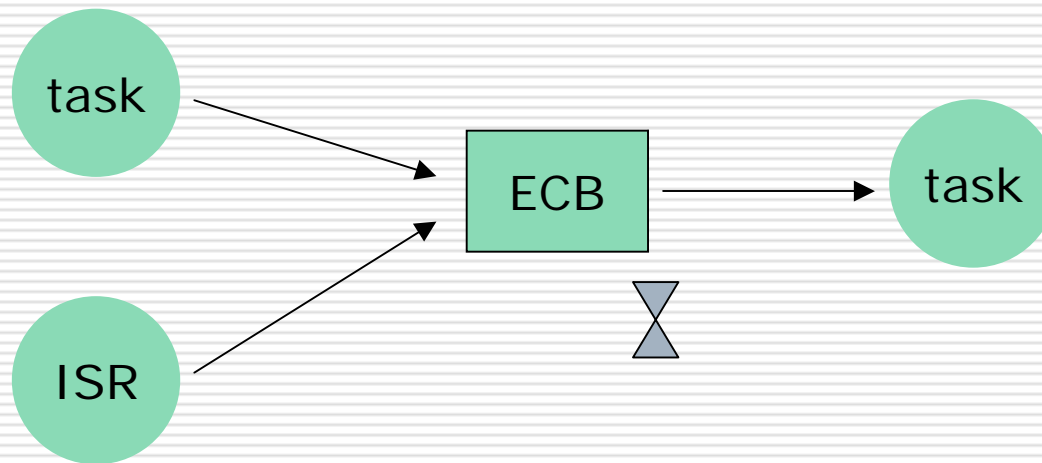
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- Introduction
  - Related Work
  - Conclusion
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# Introduction(1/4)

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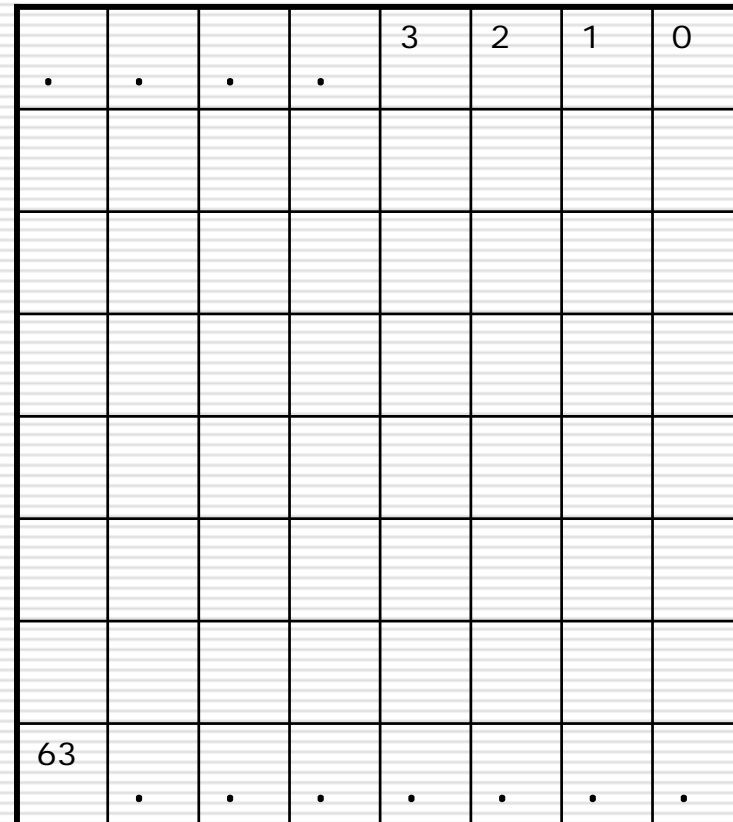
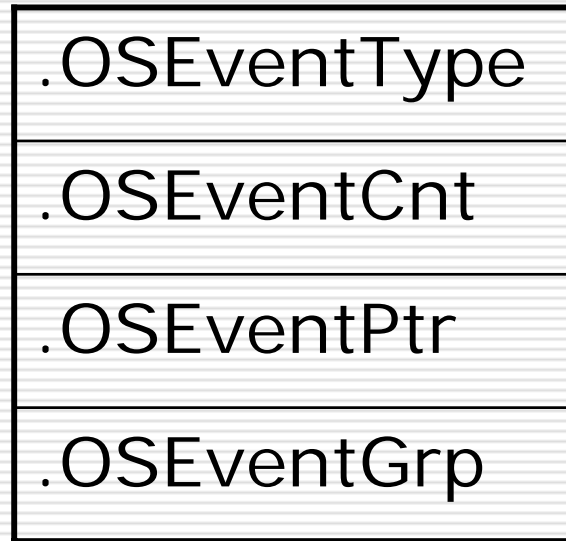
## □ ECB



# ECB(cont.)

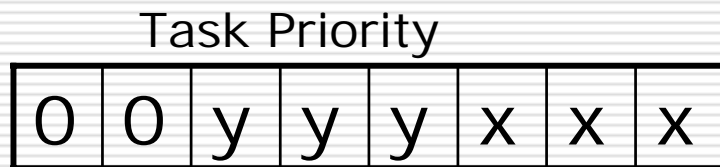
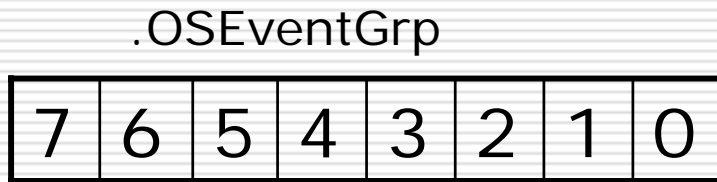
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pevent →



# ECB(cont.)

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[0]				3	2	1	0
[1]	.	.	.	.			
[2]							
[3]							
[4]							
[5]							
[6]							
[7]	63	.	.	.	.	.	.

.OSEventTbl[]

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# Introduction(2/4)

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- Placing a task in the wait list

```
Pevent -> OSEventGrp |= OSMapTbl[prio>>3];  
Pevent -> OSEventTbl[prio>>3] |= OSMapTbl[prio & 0x07];
```

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# Introduction(3/4)

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- Removeing a task from a wait list

```
If((pevent->OSEventTbl[prio>>3] &= ~OSMapTbl[prio &= 0x07])=0)
{
    pevent ->OSEventGrp &= OSMapTbl[prio>>3];
}
```

# Introduction(4/4)

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- Find the highest priority task

```
Y=OSUnMapTbl[pevent ->OSEventGrp];  
X=OSUnMapTbl[pevent ->OSEventTbl[y]];  
Prio = (y<<3) +x ;
```



# Example

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- .OSEventGrp contains 11001000(binary) and .OSEventTbl[3] contains 00010000(binary) , what is the waiting task priority ?

Some OSUnMapTb[]

```
4, 0, 1, 0, 2, 0, 1, 0, 3, 0, 1, 0, 2, 0, 1, 0 /* 0x10 to 0x1F */  
6, 0, 1, 0, 2, 0, 1, 0, 3, 0, 1, 0, 2, 0, 1, 0 /* 0xC0 to 0xCF */
```

Answer : prio=28

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# Related Work(1/4)

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## □ Initializing an ECB

```
void OS_EventWaitListInit(OS_Event *pevent){
    INT8U *ptbl;
    pevent->OSEventGrp =0x00;
    ptbl                = &pevent-> OSEventTbl[0];
#if OS_EVENT_TBL_SIZE >0
    *ptbl++            =0x00;
#endif
#if OS_EVENT_TBL_SIZE >1
    *ptbl++            =0x00;
#endif
#if OS_EVENT_TBL_SIZE >2
    *ptbl++            =0x00;
#endif
#if OS_EVENT_TBL_SIZE >3
    *ptbl++            =0x00;
#endif
}
```

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# Initializing an ECB(cont.)

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```
#if OS_EVENT_TBL_SIZE >4
    *ptbl++      =0x00;
#endif
#if OS_EVENT_TBL_SIZE >5
    *ptbl++      =0x00;
#endif
#if OS_EVENT_TBL_SIZE >6
    *ptbl++      =0x00;
#endif
#if OS_EVENT_TBL_SIZE >7
    *ptbl        =0x00;
#endif
}
```

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# Related Work(2/4)

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## □ Making a task ready

```
INT8U OS_EventTaskRdy(OS_EVENT *pevent, void *msg,
INT8U msk)
{
    OS_TCB *ptcb;
    INT8U x;
    INT8U y;
    INT8U bitx;
    INT8U bity;
    INT8U prio;

    y=OSUnMapTbl[pevent->OSEventGrp];
    bity=OSMapTbl[y];
    x=OSUnMapTbl[pevent->OSEventTbl[y]];
    bitx=OSMapTbl[x];
```

# Making a task ready(cont.)

```
prio=(INT8U)((y<<3) + x);
if((pevent->OSEventTbl[y] &= ~bitx) = 0x00){
    pevent->OSEventGrp &= ~bity;
}
Ptcb =OSTCBPrioTbl[prio];
Ptcb->OSTCBEventPtr = (OS_EVENT *)0;
#if ((OS_Q_EN>0)&&(OS_MAX_OS>0)) || (OS_MBOX_EN >0)
    ptcb->OSTCBMsg = msg;
#else
    msg = msg;
#endif
ptcb->OSTCBStat &= ~msk;
if(ptcb->OSTCBStat = OS_STAT_RDY){
    OSRdyGrp    |=bity;
    OSRdyTbl[y] |=bitx;
}
return(prio);
}
```

# Related Work(3/4)

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## □ Making a waiting task

```
void OS_EventTaskWait(OS_EVENT *pevent){
    OSTCBCur->OSTCBEventPtr = pevent ;
    if((OSRdyTbl[OSTCBCur->OSTCUBY] &= ~OSTCBCur->
OSTCBBitx) = 0x00 ){
        OSRdyGrp &= ~OSTCBBity;
    }
    pevent->OSEventTbl[OSTCUBY] |= OSTCBCur->OSTCBBitX;
    pevent->OSEventGrp |=OSTCBCur->OSTCBBity;
}
```

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# Related Work(4/4)

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- ❑ Making a task ready because of time out

```
void OS_EventTO(OS_EVENT *pevent){
    if((pevent->OSEventTbl[OSTCBCur->OSTCBBY] &=
~OSTCBCur->OSTCBBitx) = 0x00 ){
        pevent->OSEventGrp &= ~OSTCBCur->OSTCBBity;
    }
    OSTCBCur->OSTCBStat = OS_STAT_RDY;
    OSTCBCur->OSTCBEventPtr = (OS_EVENT *)0;
}
```

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# Conclusion

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Thank you